



Lightweight Agile Robotic Assistant

Performance meets cost efficiency.





# Combining the agility of lightweight design with industrial performance.



Payload 3-15 kg



Speed
Up to 200 °/s



**Reach** 590 - 1300 mm



Weight 17-55 kg

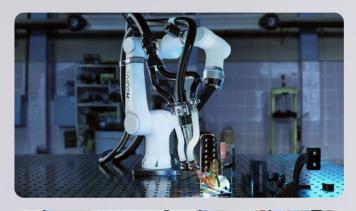


With unmatched speed, precision and protection, LARA bridges the gap between the world of collaborative and industrial robots. This way, LARA allows you to automate any production process in a cost efficient way.



# Made for any use case.

LARA is your first choice for automating simple and repetitive tasks, helping you to save costs and maximize revenue. No matter the environment.















## LARA





## A maxiumum of efficiency.



## **Technology**

First-class performance through state-of-the-art components such as the integrated 24-bit encoders, which are among the highest-resolution on the market.



## Cost-efficiency

With all major components developed and manufactured in-house, LARA is competitively priced and allows anyone to enter the world of collaborative robots.



## Safety

Its proprietary safety architecture as well as features such as definition of safety positions, speed, torque, zones, limits and collision detection allows LARA to be used in shared environments with humans.



## Highest precision

LARA can safely handle all types of delicate parts and assemble objects with consistent force, eliminating waste and preventing costly collisions.



## Well protected

Thanks to its compact and robust design and IP66 rating, LARA can be used in all kinds of harsh environments that may not be suitable for other collaborative robots. In addition, dirt can be easily washed off.



## Maximum flexibility

To meet your individual needs, LARA comes in several variants with different reach (590-1300 mm) and payload (3-15 kg), all with six degrees of freedom.



## Ready to go

Combining MAV with a collaborative or cognitive robot enables complete process automation, significantly reducing the time required for a single operation.

The combination of this system with a shelf allows smooth handling of all types of production parts.



## Customizable

Individual painting ensures a perfect match with your surroundings. With additional sensor packages such as a 3D camera module as a flange, LARA can use robot vision for object recognition, autonomous gripping or quality inspection without any effort.

## All the interfaces

LARA covers all common interfaces such as EtherCAT, IO-Link, CAN, Modbus and GPIO. The TCP connector flange offers digital I/O ports (in/out), analog in ports, and 24V 600 mA power supply.





# LARA is for everyone.

LARA is your first choice for automating simple and repetitive tasks, helping you to save costs and maximize revenue. No matter the environment.

# Drag & drop system

Configuration wizards buttons

Dynamic path and force recording

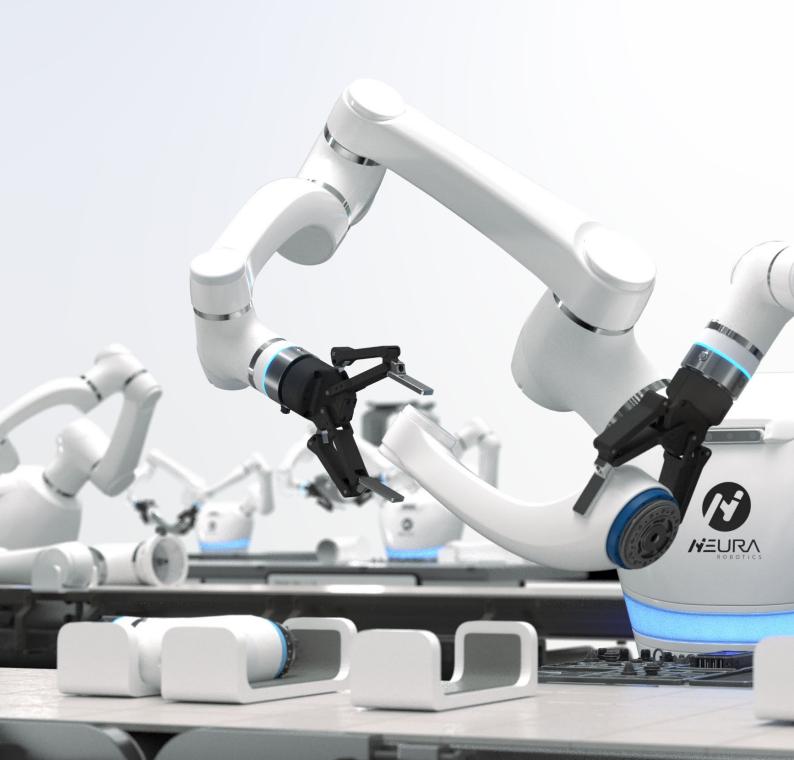
Programmable buttons on TCP





## LARA Dual power

The creation of a dual-arm platform with two LARA robots enables the efficient handling of demanding tasks such as quality inspection and synchronized co-manipulation of any object.





## **Benefits**

## Cycle time reduction

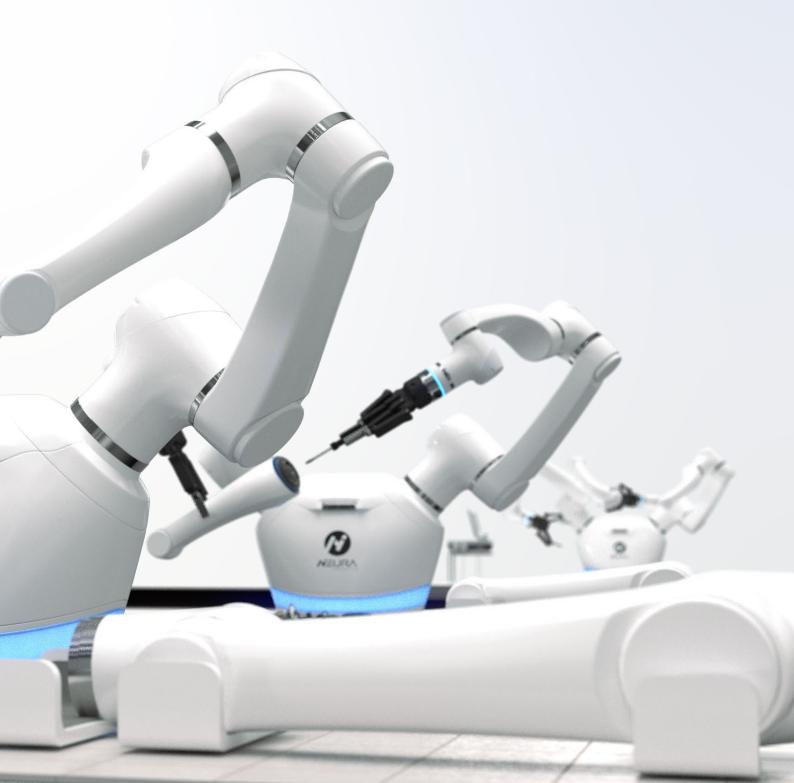
No repeated setting down and picking up to realign the workpiece.

## Maximum flexibility

No customized fixtures and process steps are required.

## Improved quality

Manipulation of objects far beyond human precision capabilities.











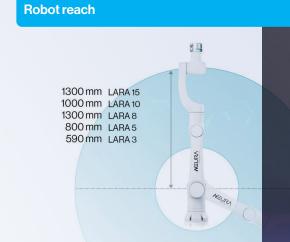
# Technical specifications

General specs	LARA 3	LARA 5	LARA 8	LARA 10	LARA 15
Payload	3kg	5kg	8kg	10 kg	15 kg
Reach	590 mm	800 mm	1300 mm	1000 mm	1300 mm
Degrees of Freedom	6 rotary joints				
Weight	17 kg	26 kg	48 kg	42 kg	55 kg
Robot mounting	Any orientation				
IP classification	IP66	IP66	IP66	IP66	IP54
Ambient working temperature	0°C-50°C	0°C-50°C	0°C-50°C	0°C-50°C	0°C-50°C
Data & power cables	Complete inner harness				
Footprint base	Ø 156 mm	Ø 156 mm	Ø 200 mm	Ø 200 mm	Ø 200 mm
Tool connector type	M1212-pole	M1212-pole	M1212-pole	M1212-pole	M1212-pole
Status illumination	RGB LED on TCP				
Tgt. perf. level	PLd Cat.3 / SIL3	PLd Cat.3/SIL3	PLd Cat.3/SIL3	PLd Cat.3/SIL3	PLd Cat.3/SIL3
Tgt. repeatability	± 0.02 mm				

Movement				
Axis	Working angles	Maxii	Maximum speed	
	LARA 3/5/8/10/15	LARA 3/5	LARA 8/10/15	
A1	± 180°	200°/s	140°/s	
A2	± 135°	200°/s	140°/s	
A3	± 155°	200°/s	200°/s	
A4	± 180°	200°/s	200°/s	
A5	± 180°	220°/s	220°/s	
A6	±360°	220°/s	220°/s	



TCP Connector Flange	e
Hole pattern	DIN ISO 9409-1-50-4-M6
GPIO	3x digital in, 3x digital out, 2x analog in
I/O port	M1212-pin-A-M / IEC 61076-2-101
I/O power supply	24V 1.5 A
Electrical interfaces	GPIO, Modbus RTU, 24V PSU
Control functions	2 programmable buttons on TCP



Software & Controller		
Motion controller	Real-Time NR-Motion Master	
Software interfaces	Robot API	
Safety architecture	Safe Master	
Safety features	Safe position, speed, torque, limits	

Programming features			
Smart GUI	NR easy programming interface		
Fast programming	Programmable buttons on TCP, ZeroG, path recording		
Human-robot- interaction	GUI, force-feedback, LED indicator on TCP		



Control box	~
Dimensions	450 mm x 380 mm x 210 mm 17.7 in x 15 in x 8.3 in
Weight	25 kg/55.1 lbs
Power supply	100-240 VAC, 50/60 Hz, 2.3 kW
Interfaces	TCP/IP, GPIO, Modbus TCP, USB 3.0, Safe I/Os

Tech pendant	1	
Dimensions	285 mm x 228 mm 11.2 in x 9 in x 3.7 in	x 95 mm
Resolution	2560x1600	
Cable length	5 m / 197 in	
	7	5.73 (3.73)

#### Note:

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# LARA next-level flexibility





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